# Homomorphisms and Short Exact Sequences of Skew 

## Bracoids

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3^{\text {rd }} \text { of August } 2023
$$

## Outline

(1) Basic Definitions and Substructures
(2) Homomorphisms and Isomorphisms
(3) Images and Kernels

4 A Motivating Example

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(1) Basic Definitions and Substructures

## (2) Homomorphisms and Isomorphisms

(3) Images and Kernels

## The Objects at Play

## Definition

A skew (left) brace is a triple ( $G, \star, \circ$ ), where $(G, \star)$ and $(G, \circ)$ are groups and for all $g, h, f \in G$

$$
g \circ(h \star f)=(g \circ h) \star g^{-1} \star(g \circ f) .
$$

## Definition

A skew (left) bracoid is a 5 -tuple ( $G, \cdot, N, \star, \odot$ ), where ( $G, \cdot$ ) and ( $N, \star$ ) are groups and $\odot$ is a transitive action of $G$ on $N$ for which

$$
g \odot(\eta \star \mu)=(g \odot \eta) \star\left(g \odot e_{N}\right)^{-1} \star(g \odot \mu),
$$

for all $g \in G$ and $\eta, \mu \in N$.

## Housekeeping

- We will assume everything is finite.
- We will frequently write $(G, N, \odot)$, or even $(G, N)$, for $(G, \cdot, N, \star, \odot)$.
- We will refer to $(N, \star)$ as the additive group and $(G, \cdot)$ as the multiplicative or acting group.
- Any identity will be denoted $e$, possibly with a subscript.


## For example

## Examples

- Any skew brace $(G, \star, \circ)$ can be thought of as a skew bracoid $(G, \circ, G, \star, \odot)$, where $\odot$ is simply $\circ$.


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- For any group $(G)$ we have the skew bracoid $(G,\{e\}, \odot)$ where of course the action $\odot$ is trivial.


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- For any group $(G)$ we have the skew bracoid $(G,\{e\}, \odot)$ where of course the action $\odot$ is trivial.
- Let $d, n \in \mathbb{N}$ such that $d \mid n$. Take
$G=\left\langle r, s \mid r^{n}=s^{2}=e, s r s^{-1}=r^{-1}\right\rangle \cong D_{n}$ and $N=\langle\eta\rangle \cong C_{d}$. Then we get a skew bracoid $(G, N, \odot)$ for $\odot$ given by

$$
r^{i} s^{j} \odot \eta^{k}=\eta^{i+(-1)^{j} k}
$$

## The $\gamma$-functions

## Definition/Proposition

Let $(G, N, \odot)$ be a skew bracoid and $g \in G$. The map $\gamma_{g}: N \rightarrow N$ given by

$$
\gamma_{g}(\eta)=\left(g \odot e_{N}\right)^{-1}(g \odot \eta)
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is in fact an automorphism of $N$.

We call these maps associated with the skew bracoid the $\gamma$-functions of the skew bracoid.

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We can use these maps to embed $G$ into $\operatorname{Hol}(N)$ via $g \mapsto\left(g \odot e_{N}, \gamma_{g}\right)$. Morally, this amounts to killing off any kernel of the action $\odot$.

## Substructures

Let $(G, N, \odot)$ be a skew bracoid.

## Definition

The triple $(H, M, \odot)$ is a sub-skew bracoid of $(G, N, \odot)$ if and only if

- $H$ is a subgroup of $G$,
- $M$ is a subgroup of $N$,
- and $H$ acts transitively on $M$ via $\odot$.


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## Definition

A normal subgroup $M$ of $N$ is an ideal of $(G, N, \odot)$ if and only if it is closed under $\gamma_{g}$ for all $g \in G$.

## Quotients

## Proposition

Let $(G, N, \odot)$ be a skew bracoid with $M$ an ideal. We have that $G$ acts on the quotient group $N / M$ via $g \odot(\eta M):=(g \odot \eta) M$, and $(G, N / M, \odot)$ is a skew bracoid.

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## Homomorphisms

## Definition

A homomorphism of skew bracoids between $(G, N, \odot)$ and $\left(G^{\prime}, N^{\prime}, \odot^{\prime}\right)$ is a pair of group homomorphisms $\varphi: G \rightarrow G^{\prime}$ and $\psi: N \rightarrow N^{\prime}$ such that

$$
\psi(g \odot \eta)=\varphi(g) \odot^{\prime} \psi(\eta)
$$

for all $g \in G$ and $\eta \in N$.

## An alternative framing

Let $\varphi: G \rightarrow G^{\prime}$ be a homomorphism of groups.

If $\varphi\left(\operatorname{Stab}_{G}\left(e_{N}\right)\right) \subseteq \operatorname{Stab}_{G^{\prime}}\left(e_{N^{\prime}}\right)$ then we have a well-defined map $\varphi_{N}: N \rightarrow N^{\prime}$ given by

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\varphi_{N}\left(g \odot e_{N}\right):=\varphi(g) \odot^{\prime} e_{N^{\prime}}
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If this $\varphi_{N}$ turns out to be a homomorphism itself then the pair, $\varphi$ and $\varphi_{N}$, forms a homomorphism of skew bracoids.

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If this $\varphi_{N}$ turns out to be a homomorphism itself then the pair, $\varphi$ and $\varphi_{N}$, forms a homomorphism of skew bracoids.

Conversely every homomorphism of skew bracoids is necessarily of this form.

## Notation

With this in mind, we set the following convention:

- $\varphi$ denotes the pair of homomorphisms that form the skew bracoid homomorphism,
- $\varphi$ denotes the homomorphism between the acting groups,
- and $\varphi_{N}$ the (induced) homomorphism between the additive groups.


## Isomorphism and Equivalence

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## Definition

We say that two skew bracoids $(G, N, \odot)$ and $\left(G^{\prime}, N^{\prime}, \odot^{\prime}\right)$ are equivalent if and only if $N=N^{\prime}$ and the image of $G$ and the image of $G^{\prime}$ in $\operatorname{Hol}(N)$ coincide.

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This has the uncomfortable consequence that a homomorphism can be injective and surjective, but not an isomorphism. We can take comfort in the fact that it will be an isomorphism, up to our notion of equivalence.

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## Images and Kernels

## Proposition

Let $\varphi:(G, N, \odot) \rightarrow\left(G^{\prime}, N^{\prime}, \odot^{\prime}\right)$ be a homomorphism of skew bracoids then

- $\operatorname{ker}\left(\varphi_{N}\right)$ is an ideal of $(G, N, \odot)$,
- and $\left(\operatorname{im}(\varphi), \operatorname{im}\left(\varphi_{N}\right), \odot^{\prime}\right)$ is a sub-skew bracoid of $\left(G^{\prime}, N^{\prime}, \odot^{\prime}\right)$.


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## Definition

The image of the homomorphism $\varphi$ is $\operatorname{im}(\varphi):=\left(\operatorname{im}(\varphi), \operatorname{im}\left(\varphi_{N}\right)\right)$.

## Kernel For Our Purposes

Remember our goal is to develop a notion of short exact sequence for skew bracoids. For there to be any hope of the kernel of a homomorphism and the image of a homomorphism aligning, we need them to be the same kind of object.

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## Naive Attempt: $\left(\operatorname{ker}(\varphi), \operatorname{ker}\left(\varphi_{N}\right)\right)$

Consider the (toy) example $\varphi:\left(D_{3}, C_{3}\right) \rightarrow\left(D_{3},\{e\}\right)$ where $\varphi$ is just the identity, and $\varphi_{N}(\eta)=e$ for all $\eta \in C_{3}$.

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But $\operatorname{ker}(\varphi)=\{e\}$ and $\operatorname{ker}\left(\varphi_{N}\right)=C_{3}$, so $\operatorname{ker}(\varphi)$ does not act transitively on $\operatorname{ker}\left(\varphi_{N}\right)$ and thus we so not have a skew bracoid.

## For Our Purposes

## Proposition (Intelligent Attempt)

Let $\varphi:(G, N, \odot) \rightarrow\left(G^{\prime}, N^{\prime}, \odot^{\prime}\right)$ be a homomorphism of skew bracoids and $S^{\prime}=\operatorname{Stab}_{G^{\prime}}\left(e_{N^{\prime}}\right)$. The triple $\operatorname{ker}(\varphi):=\left(\varphi^{-1}\left(S^{\prime}\right), \operatorname{ker}\left(\varphi_{N}\right), \odot\right)$ is a sub-skew bracoid of $(G, N, \odot)$.

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- In our toy example $S^{\prime}=D_{3}$ and $\varphi^{-1}\left(D_{3}\right)=D_{3}$ so that our "kernel" is $\left(D_{3}, C_{3}\right)$. Certainly a skew bracoid.
- Specialising to the skew brace case, this stabiliser will necessarily be trivial so its inverse image is precisely the kernel of $\varphi$.
- This lands on the associated subgroup in $G$ of $\operatorname{ker}\left(\varphi_{N}\right)$, our standard lift from an ideal in the additive group to subgroup of the acting group.


## Short Exact Sequence

Then a short exact sequence of skew bracoids is given by

$$
e \longrightarrow\left(G_{1}, N_{1}\right) \xrightarrow{\varphi}\left(G_{2}, N_{2}\right) \xrightarrow{\psi}\left(G_{3}, N_{3}\right) \longrightarrow e
$$

where $\varphi$ and $\psi$ are homomorphisms of skew bracoids such that

$$
\operatorname{im}(\varphi)=\operatorname{ker}(\psi)
$$

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## The Correspondence between Hopf-Galois Structures and

## Skew Bracoids

Let $L / K$ be a separable extension of fields with Galois closure $E$, and write $(G, \cdot)=\operatorname{Gal}(E / K)$ and $S=\operatorname{Gal}(E / L)$. Recall

## Theorem

There is a bijective correspondence between

- Hopf-Galois structures on $L / K$ and
- operations $\star$ such that $(G, \cdot, G / S, \star, \odot)$ forms a skew bracoid, where $\odot$ is left translation of cosets via .



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## Almost Classical Hopf-Galois Structures

## Definition

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## Definition

A Hopf-Galois structure is almost classical if it corresponds under Greither-Pareigis to a subgroup of $\operatorname{Perm}(G / S)$ of the form $\lambda(H)^{\text {opp }}$, for some normal complement $H$ of $S$.

## Almost Classical Skew Bracoids

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Let $(G, N)$ be a skew bracoid and $S=\operatorname{Stab}_{G}\left(e_{N}\right)$. We say $(G, N)$ is almost classical if $S$ has a normal complement $H$ in $G$ for which $(H, N)$ is essentially a trivial skew brace.

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This means that for all $h_{1}, h_{2} \in H$ we have

$$
h_{1} h_{2} \odot e_{N}=\left(h_{1} \odot e_{N}\right)\left(h_{2} \odot e_{N}\right)
$$

## For Example

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We can take $(G, N, \odot)$ with $G=\langle r, s| r^{3}=s^{2}=e$, srs $\left.^{-1}=r^{-1}\right\rangle \cong D_{3}$, $N=\langle\eta\rangle \cong C_{3}$, with $\odot$ given by

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r^{i} s^{j} \odot \eta^{k}=\eta^{i+(-1)^{j} k} . \tag{1}
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- Putting $k=0$ in (1), we get $r^{i} s^{j} \odot e_{N}=\eta^{i}$. We stabilise $e_{N}$ precisely when $i=0$, so $\operatorname{Stab}_{G}\left(e_{N}\right)=\langle s\rangle$.


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- For $0 \leq i, j \leq 2$, we have $\left(r^{i} \odot e\right)\left(r^{j} \odot e\right)=\eta^{i+j}=r^{i} r^{j} \odot e$.


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Hence we have an almost classical skew bracoid.

## Induced Hopf-Galois Structures



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Here $N \subseteq \operatorname{Perm}(S)$ and $M \subseteq \operatorname{Perm}(G / S)$

## Induced Hopf-Galois Structures



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Again take $(G, \cdot)=\langle r, s\rangle \cong D_{3}$ and $(S, \cdot)=\langle s\rangle \cong C_{2}$.

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We have the trivial skew brace $(S, \cdot, \cdot)$ and the almost classical skew bracoid $(G, G / S)$ with $G / S \cong\langle r\rangle$. Taking the direct product of $G / S$ and $S$ we get a cyclic group of order 6 generated by $(r S, s)$ for example. Associating $(r S, e)$ with $r$ and $(e S, s)$ with $s$, we get a skew brace $(G, \star, \cdot)$ where $(G, \star) \cong C_{6}$ and $(G, \cdot) \cong D_{3}$.

## The Short Exact Sequence

With this machinery in tow we have the following.

## Proposition

Let $(G, H)$ be an almost classical skew bracoid and $S=\operatorname{Stab}_{G}\left(e_{H}\right)$. We have the short exact sequence

$$
e \longrightarrow(S, S) \longleftrightarrow(G, H \times S) \longrightarrow(G, H) \longrightarrow e .
$$

## Thank you for your attention!

